
Probabilistic Computing via Sparse Distributed Representations

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Two Approaches to Non-Binary Computing

Lyric

- Lowest-level signals in system are represented as continuous-valued
- A voltage level on a single wire communicates, in a single transmission cycle, e.g., an 8-bit, quantity, e.g., interpretable as a probability.
- In conventional computing, 8 signals, each a binary voltage level, have to be sent and then combined (decoded) at the destination

Neurithmic

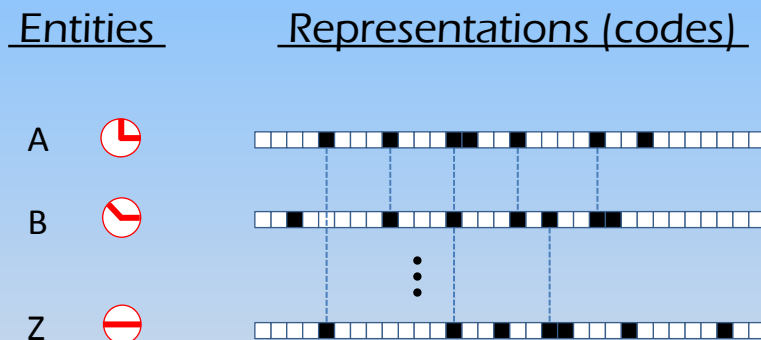
- Lowest-level signals are represented as binary-valued
- All represented values, i.e. of:
 - variables
 - relationships between variables, e.g., conditional probabilities

are represented as *sums* of binary signals

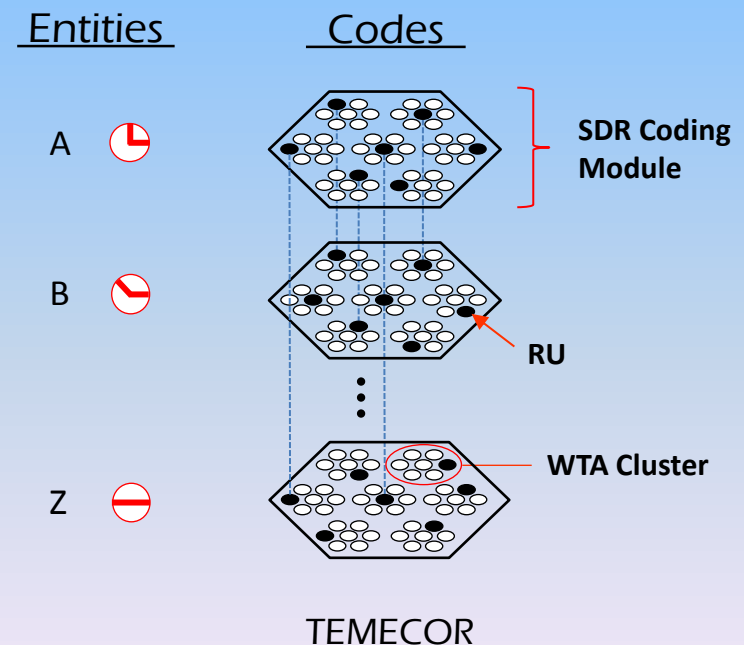
Sparse Distributed Representation

- Every represented entity in the system is represented by a subset of binary representational units (RUs) chosen from a much larger set.
- The subsets can overlap
- It's possible to represent similarity of entities by overlap of their codes

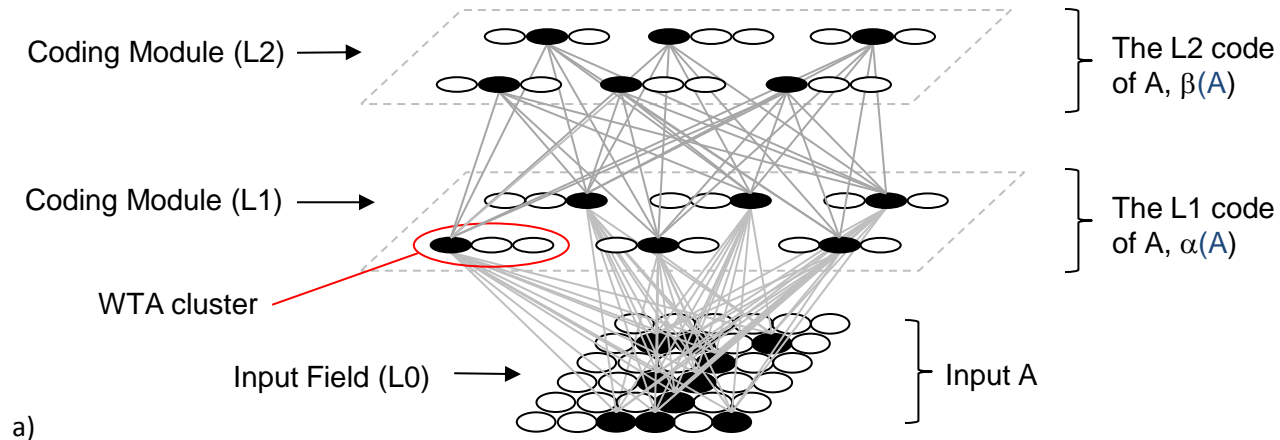
Similar-inputs-to-similar-codes (SISC) property



e.g., Kanerva, Willshaw et al, Palm



Realizing SISC via SDR



Representation (Code)

Input

Name

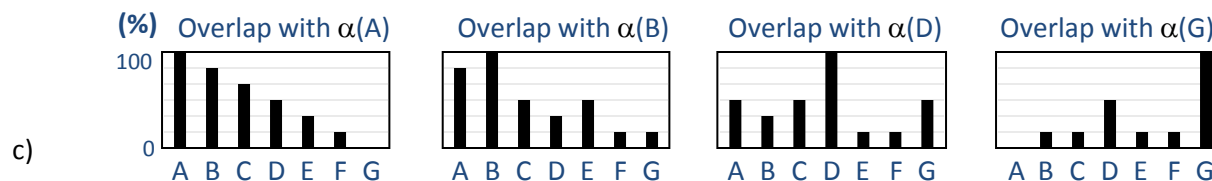
Physical Realization

Overlap with $\alpha(A)$

A	$\alpha(A)$							6 / 6
B	$\alpha(B)$							5 / 6
C	$\alpha(C)$							4 / 6
D	$\alpha(D)$							3 / 6
E	$\alpha(E)$							2 / 6
F	$\alpha(F)$							1 / 6
G	$\alpha(G)$							0 / 6

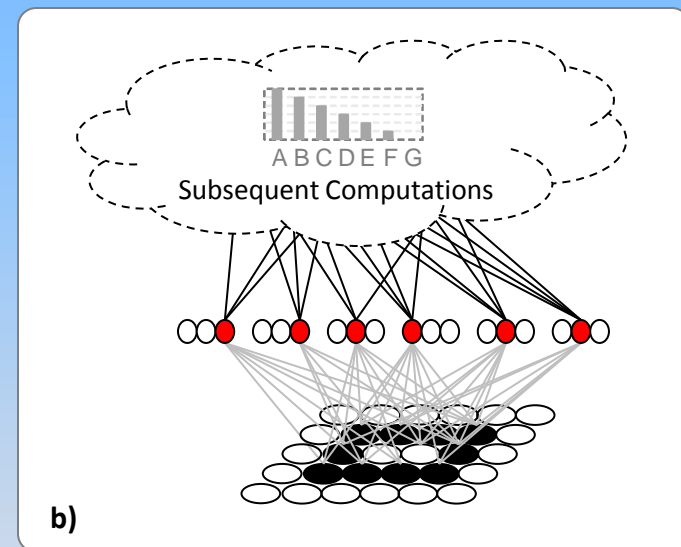
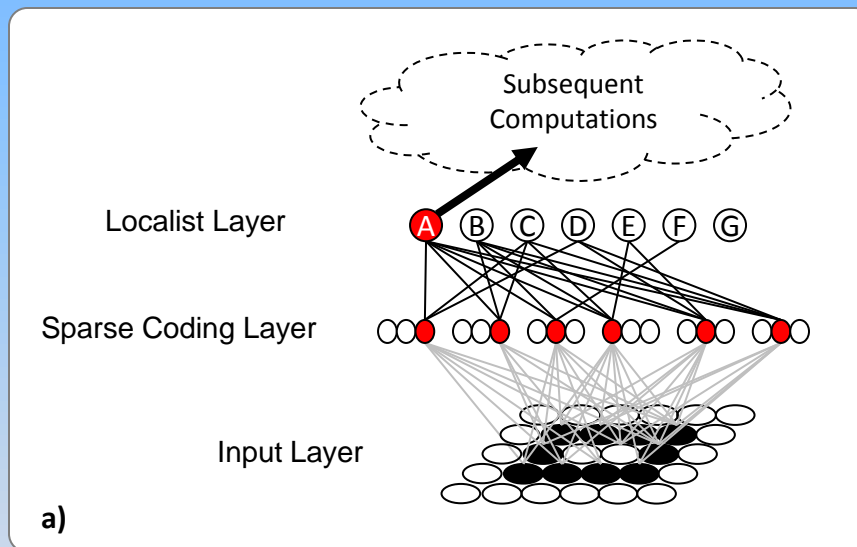
b)

Any single code represents ALL stored codes



Not Forcing Computation Through a Localist Nexus

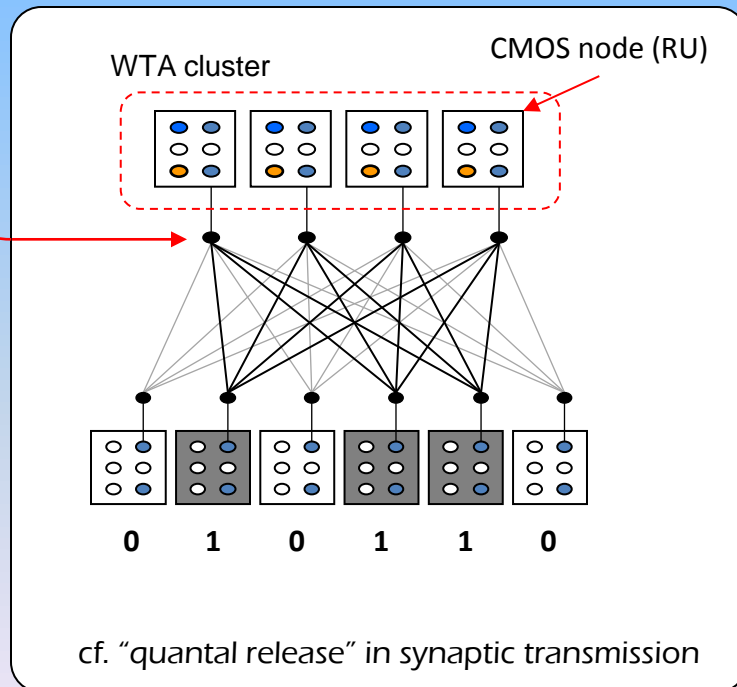
- Any single code represents ALL stored codes



Summing Binary Signals

Physically

- Voltages sum simultaneously on terminal.
- No decoding needed



Algorithmically

- Involves iterating over RUs and over each RU's set of incoming weights.
- These are fixed quantities
- → Constant time complexity

- For each RU, i
 - Sum = 0;
 - For all incoming wts, w_{ji}
 - $\text{sum}_i += w_{ji} * a_j$

- For each RU, i
 - $a_i = f(\text{sum}_i)$



- Choose winner (soft max)

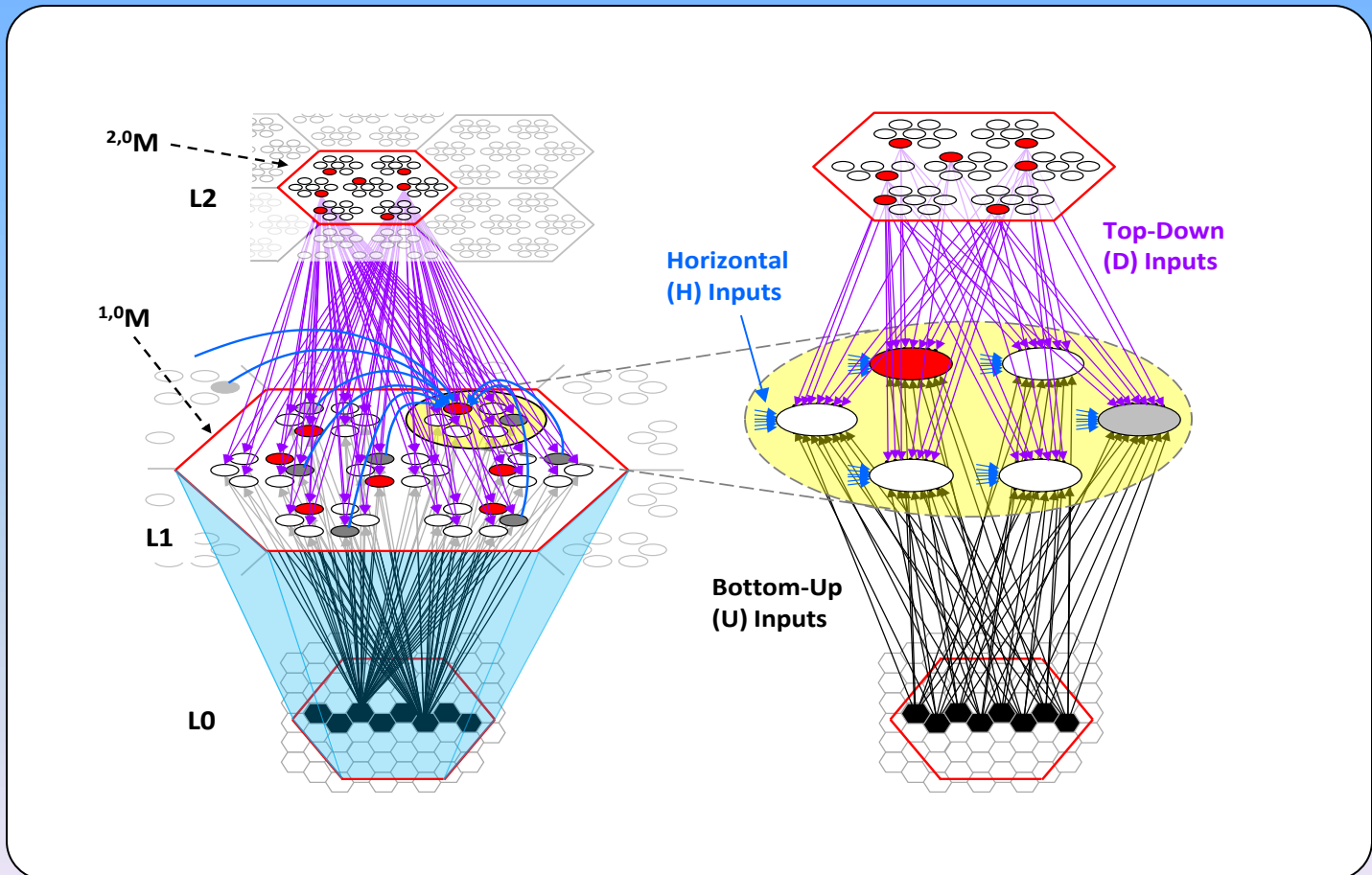
Set up cumulative distribution of a_i

Generate rand. num. in the range

1
20
1800
1810

Three evidence sources combine to select codes

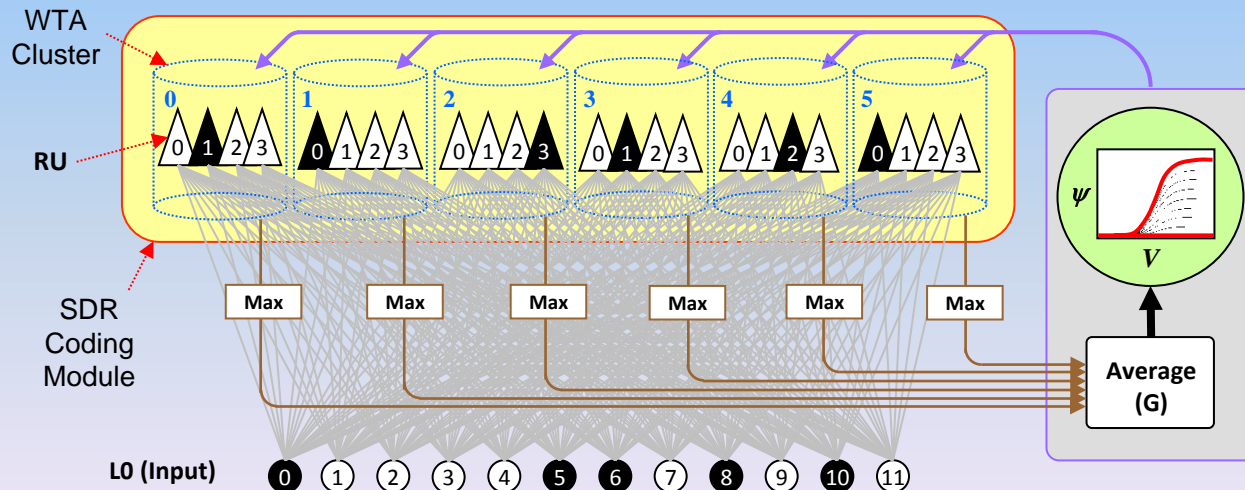
- Bottom-up, Horizontal, and Top-down evidence vectors are combined to choose which code becomes active.



Code Selection Algorithm

1. For each RU, sum its inputs.
2. Normalize each sum to [0..1] range.
3. Multiply the three normalized sums, yielding a *local* degree of support (evidence), V .
- ➔ 4. RU with max V in each cluster wins (1st round).
5. Compute G , the ave. of the max V s over all clusters in a coding module.
6. Modulate the RU activation function, $f(V)$, based on G :
 - As $G \rightarrow 0$, make activation function more compressive
 - As $G \rightarrow 1$, make activation function more expansive
7. For each RU, compute $\psi = f(V)$
8. In each cluster, normalize ψ 's to probability measure, ρ .
- ➔ 9. In each cluster, choose winner *as draw* from ρ distribution (2nd round)

G is a *global* (to coding module) measure of the familiarity of total input to the module.



CSA Example

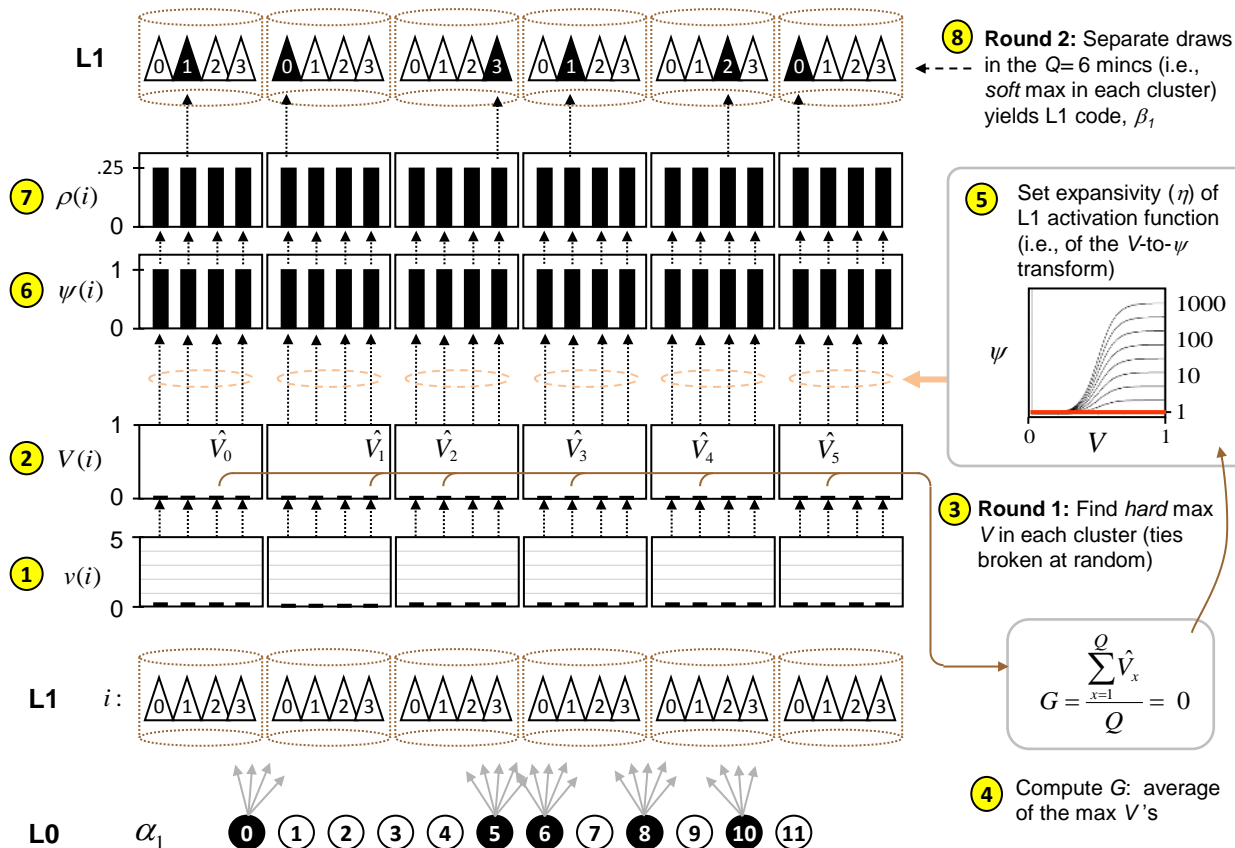


Figure 1 illustrates the hierarchical structure of a neural network model, showing the evolution of the network as the coupling strength G decreases from 1.0 to 0.0. The model is organized into two layers: L0 (input nodes) and L1 (output nodes).

Panel A: $G = 1.0$. The network is fully connected. L0 nodes are labeled 0 to 11, and L1 nodes are labeled 0 to 5. The coupling strength $G = 1.0$ is indicated. The network structure is shown with all connections between L0 and L1 nodes. The L1 nodes are labeled with their degree of connectivity, β_2 , and the L0 nodes are labeled with their degree of connectivity, α_2 . The intersection of β_2 and α_1 is 6, and the intersection of α_2 and α_1 is 5.

Panel B: $G = 0.8$. The network structure is shown with some connections removed. The L1 nodes are labeled with their degree of connectivity, β_3 , and the L0 nodes are labeled with their degree of connectivity, α_3 . The intersection of β_3 and α_1 is 4, and the intersection of α_3 and α_1 is 4.

Panel C: $G = 0.4$. The network structure is shown with further connections removed. The L1 nodes are labeled with their degree of connectivity, β_4 , and the L0 nodes are labeled with their degree of connectivity, α_4 . The intersection of β_4 and α_1 is 2, and the intersection of α_4 and α_1 is 2.

Panel D: $G = 0$. The network structure is shown with all connections removed. The L1 nodes are labeled with their degree of connectivity, β_5 , and the L0 nodes are labeled with their degree of connectivity, α_5 . The intersection of β_5 and α_1 is 1, and the intersection of α_5 and α_1 is 0.

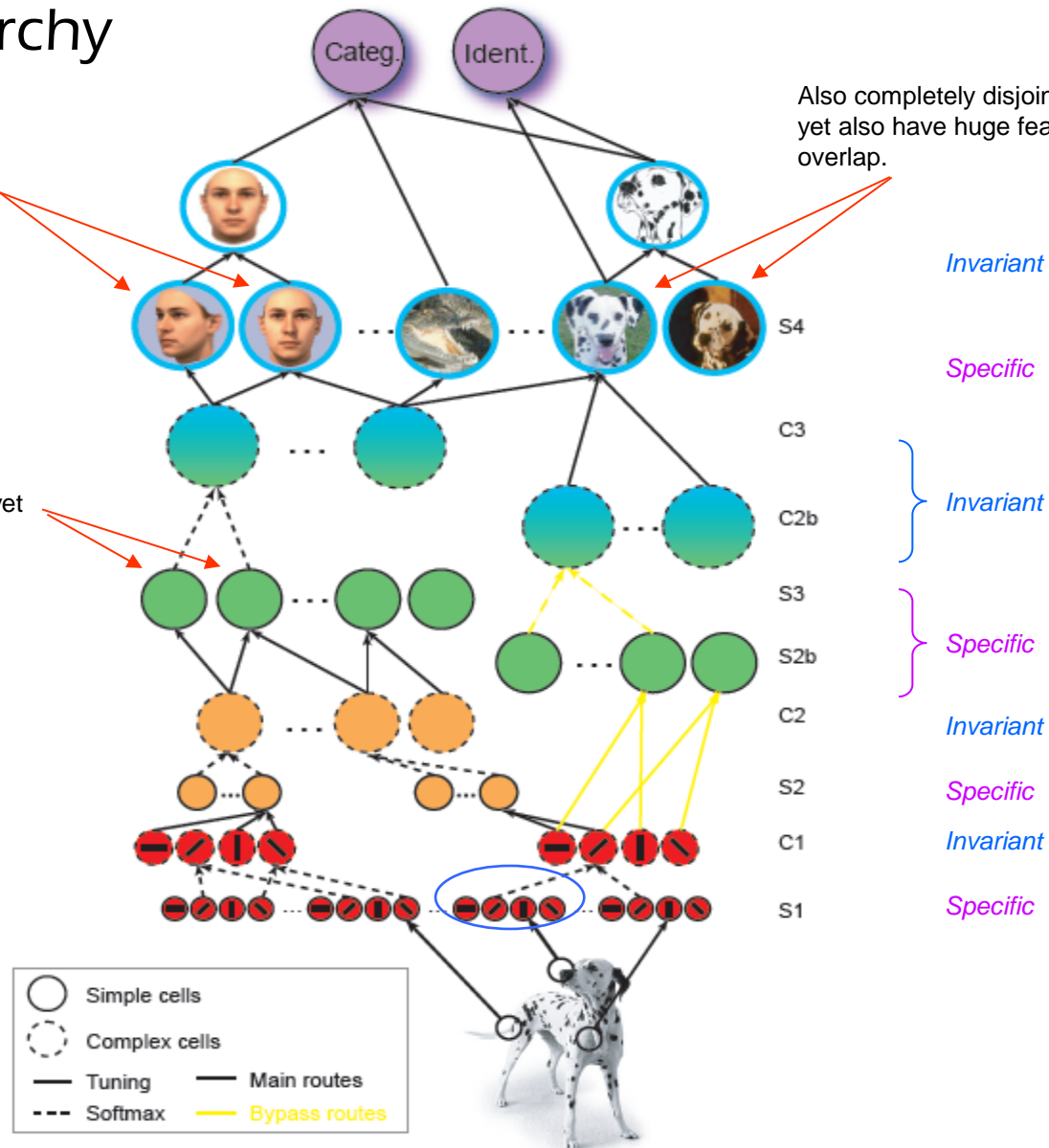
Localist Hierarchy

These two units are completely disjoint, yet they have huge featural overlap.

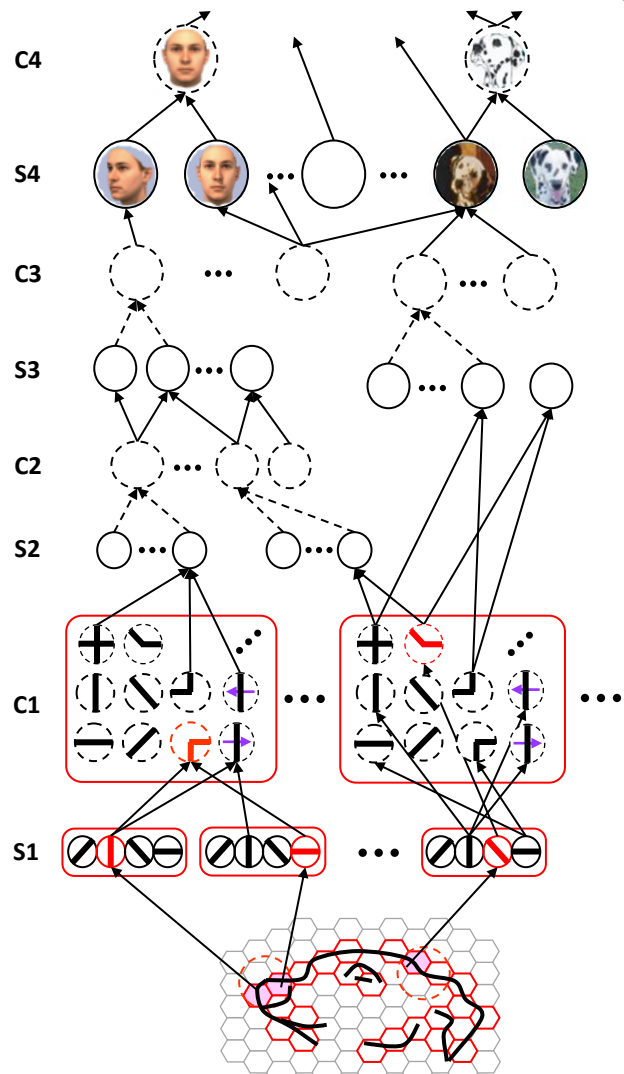
This is true throughout the entire model; i.e., millions of units representing highly redundant information.

Also completely disjoint, yet also have huge featural overlap.

Also completely disjoint, yet also have huge featural overlap.

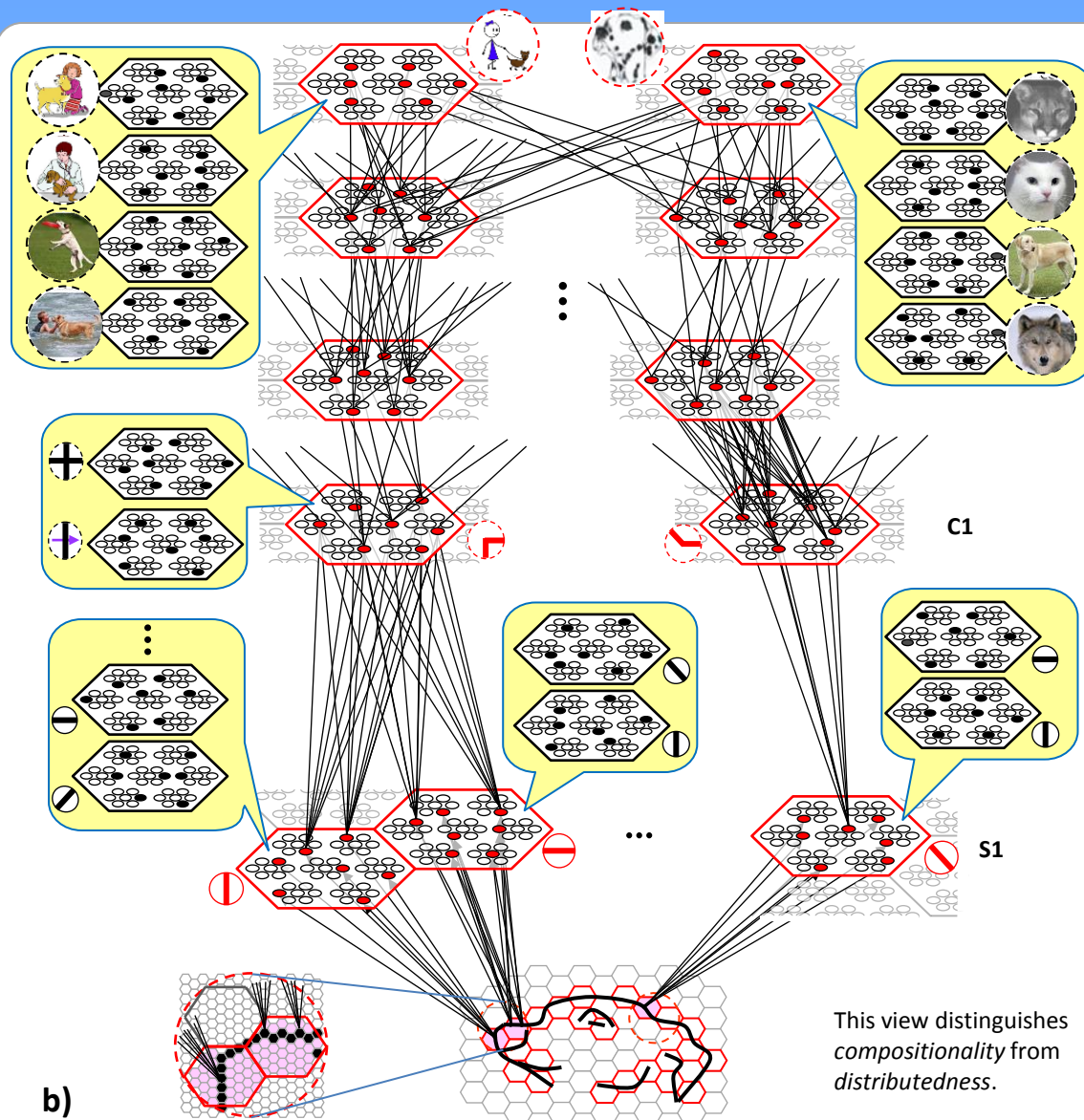


Localist vs. SDR-based Hierarchical Representations



a)

- Adapted from Serre et al (2005)



b)

This view distinguishes compositionality from distributedness.